GigaDevice Semiconductor Inc.

Migration from GD32E230 series to GD32F3x0 series

Application Note
AN046
# Table of Contents

Table of Contents .............................................................................................................. 2  
List of Figures .................................................................................................................... 3  
List of Tables ..................................................................................................................... 5  
1. Introduction ..................................................................................................................... 6  
2. Introduction to hardware differences ............................................................................. 7  
3. Comparison of resource and peripheral addresses ....................................................... 9  
4. Comparison of development tools ................................................................................. 12  
5. Software environment settings ....................................................................................... 13  
  5.1. Using Keil to develop GD32F3x0 ................................................................................. 13  
      5.1.1. Add GD32F3x0 MCU device in Keil4 ................................................................. 13  
      5.1.2. Add GD32F3x0 MCU device in Keil5 ................................................................. 15  
  5.2. Debugging and simulating GD32F3x0 with GD-Link ................................................ 17  
  5.3. Debugging and simulating GD32F3x0 with J-Link .................................................... 19  
  5.4. Using IAR to develop GD32F3x0 ............................................................................... 21  
      5.4.1. Add gd32F3x0 MCU device in IAR ................................................................. 22  
      5.4.2. Debugging GD32F3x0 in IAR ..................................................................... 22  
6. Steps of GD32E23x firmware library adapting to GD32F3x0 Series MCU .......... 26  
7. Steps to replace GD32E23x project library with GD32F3x0 Library ..................... 31  
8. Revision history .............................................................................................................. 36
List of Figures

Figure 2-1. Comparison diagram of LQFP48 package of GD32F3x0 and GD32E230xx ............ 7
Figure 2-2. Comparison diagram of QFN32 package of GD32F3x0 and GD32E230xx ............ 7
Figure 2-3. Comparison diagram of QFN28 package of GD32F3x0 and GD32E230xx .......... 8
Figure 2-4. Comparison diagram of TSSOP20 package of GD32F330/F310xx and GD32E230xx 8
Figure 2-5. Comparison diagram of LQFP32 package of GD32F310xx and GD32E230xx ........ 8
Figure 5-1. GD32F3x0 plug-in package details ................................................................. 13
Figure 5-2. Installation diagram of GD32F3x0 Series MCU plug-in package (Keil4) .......... 13
Figure 5-3. Successful installation of GD32F3x0 Series MCU plug-in package (Keil4) ....... 14
Figure 5-4. GD32F3x0 series flash algorithm file selection diagram (Keil4) ..................... 14
Figure 5-5. GD32F3x0 plug-in package details ................................................................. 15
Figure 5-6. Installation diagram of GD32F3x0 Series MCU plug-in package (Keil5) ......... 15
Figure 5-7. Successful installation of GD32F3x0 Series MCU plug-in package (Keil5) ....... 16
Figure 5-8. GD32F3x0 series flash algorithm file selection diagram (Keil5) ..................... 16
Figure 5-9. Select the "CMSIS-DAP Debugger" option in the Debug interface (Keil4) ....... 17
Figure 5-10. Select the "CMSIS-DAP Debugger" option in the Utilities interface (Keil4) ..... 18
Figure 5-11. GD-Link tool successfully connected to the target MCU(Keil4) ..................... 18
Figure 5-12. Schematic diagram of adding flash algorithm file(Keil4) ............................... 19
Figure 5-13. Schematic diagram of GD-Link simulation(Keil4) ........................................ 19
Figure 5-14. Select the "J-LINK/J-Trace Cortex" option in the Debug interface (Keil4) .... 20
Figure 5-15. Select the "J-LINK/J-Trace Cortex" option in the Utilities interface (Keil4) .... 20
Figure 5-16. J-Link tool successfully connected to the target MCU(Keil4) ....................... 20
Figure 5-17. Schematic diagram of adding flash algorithm file(Keil4) ............................... 21
Figure 5-18. Schematic diagram of J-Link simulation(Keil4) ............................................. 21
Figure 5-19. Installation diagram of GD32F3x0 Series MCU plug-in package(IAR) .......... 22
Figure 5-20. Successful installation of GD32F3x0 Series MCU plug-in package (IAR) ....... 22
Figure 5-21. Select the GD device in the IAR "Options" interface ................................. 23
Figure 5-22. Add CMSIS file in IAR "Options" interface ................................................... 24
Figure 5-23. Add ICF file in IAR "Options" interface ....................................................... 24
Figure 5-24. Select the debugger tool in the IAR "Options" interface ................................ 25
Figure 5-25. Configure flash loader in IAR "Options" interface ........................................ 25
Figure 6-1. Open GD32E23x Keil project ................................................................. 26
Figure 6-2. Select GD32F3x0 device in GD32E23x project .......................................... 26
Figure 6-3. Add the flash algorithm of GD32F3x0 ....................................................... 27
Figure 6-4. Add Cortex M4 kernel files to GD32E23x firmware library .......................... 27
Figure 6-5. Modify the contents of "gd32e23x.h" ......................................................... 27
Figure 7-1. Copy h file in CMSIS of GD32F3x0 firmware library to GD32E23x ............... 31
Figure 7-2. Copy and replace the Include and Source files in CMSIS under GD32F3x0 firmware library into GD32E23x firmware library ....................................................... 31
Figure 7-3. Copy and replace the Include and Source files in standardPeripheral under GD32F3x0 firmware library into GD32E23x firmware library ................................. 31
Migration from GD32E230 series to GD32F3x0 series

Figure 7-4. Copy the "gd32f3x0_libopt.h" file in GD32F3x0 firmware library into GD32E23x firmware library .......................................................... 31

Figure 7-5. Open the Keil project under the template file in the GD32E23x firmware library .... 32

Figure 7-6. Remove the Yellow marked files and add new files ........................................... 33

Figure 7-7. Modify the contents of "main.c", "systick.c" files ............................................. 33

Figure 7-8. Reselect GD32F3x0 MCU device ......................................................................... 34

Figure 7-9. Reselect GD32F3x0 Flash algorithm ................................................................. 34
## List of Tables

- **Table 3-1. GD32F3x0 series and gd32E230xx series resources comparison overview** ............................... 9
- **Table 3-2. GD32F3x0 series and GD32E230xx series peripheral address comparison overview** ............................... 9
- **Table 4-1. Comparison of IDE environment between GD32F3x0 series and GD32E230xx series** .......................................................................................................................... 12
- **Table 4-2. Comparison of GD32F3x0 series and GD32E230xx series debugging tools** ............................... 12
- **Table 6-1. Modify the contents of "gd32e23x.h"** ........................................................................................................ 27
- **Table 6-2. Modify the contents of "gd32e23x_misc.h"** .......................................................................................... 28
- **Table 6-3. Modify the contents of "gd32e23x_misc.c"** ................................................................................................. 28
- **Table 6-4. Modify the contents of "gd32e23x_misc.h"** .......................................................................................... 28
- **Table 6-5. Modify the contents of "gd32e23x_misc.c"** ................................................................................................. 28
- **Table 6-6. Remove the function of waiting period in GD32E23x project** ......................................................... 29
- **Table 6-7. Add half word programming to "gd32e23x_fmc.h" of GD32E23x project** ................................. 30
- **Table 6-8. Add half word programming to "gd32e23x_fmc.c" of GD32E23x project** ................................. 30
- **Table 7-1. nvic_priority_group_set function** ........................................................................................................... 34
- **Table 7-2. nvic_irq_enable function** .................................................................................................................... 35
- **Table 8-1. Revision history** .................................................................................................................................. 36
1. **Introduction**

This application note is designed to help you quickly migrate applications from GD32E230xx series MCU to GD32F3x0 series MCU.

In order to make better use of the information in this application note, you need to download it from the website www.GD32MCU.com, such as datasheet, user manual, official code and various development tools.
2. **Introduction to hardware differences**

The package types of GD32E230xx series include: TSSOP20, LGA20, QFN28, QFN32, LQFP32 and LQFP48; The package types of GD32F3x0 series include: TSSOP20 (GD32F330/F310xx series only), QFN28, QFN32, LQFP32(GD32F310xx series only), LQFP48, LQFP64(GD32F330/F350xx series only). The chip pins of the same package of the two series are compatible, see **Figure 2-1. Comparison diagram of LQFP48 package of GD32F3x0 and GD32E230xx**, **Figure 2-2. Comparison diagram of QFN32 package of GD32F3x0 and GD32E230xx**, **Figure 2-3. Comparison diagram of QFN28 package of GD32F3x0 and GD32E230xx**, **Figure 2-4. Comparison diagram of TSSOP20 package of GD32F330/F310xx and GD32E230xx**, **Figure 2-5. Comparison diagram of LQFP32 package of GD32F310xx and GD32E230xx**.

1. In the package of TSSOP20 and QFN28, PA9 and PA10 of GD32E230xx series can be mapped to PA11 and PA12. GD32F3x0 series does not have this function.
2. LQFP48 package’s pin 1 is VDD on GD32E230xx series and Vbat on GD32F3x0, that is, GD32E230xx does not support power down RTC.

**Figure 2-1. Comparison diagram of LQFP48 package of GD32F3x0 and GD32E230xx**

![Figure 2-1](image1)

**Figure 2-2. Comparison diagram of QFN32 package of GD32F3x0 and GD32E230xx**

![Figure 2-2](image2)
Migration from GD32E230 series to GD32F3x0 series

Figure 2-3. Comparison diagram of QFN28 package of GD32F3x0 and GD32E230xx

Figure 2-4. Comparison diagram of TSSOP20 package of GD32F330/F310xx and GD32E230xx

Figure 2-5. Comparison diagram of LQFP32 package of GD32F310xx and GD32E230xx
3. Comparison of resource and peripheral addresses

The resources of GD32F3x0 series and GD32E230xx series are slightly different:

1. TIMER1 is added to GD32F3x0 series, but TIMER5 is cut out (GD32F350xx has this peripheral). GD32E230xx series has TIMER5, but there is no TIMER1;
2. GD32E230xx and GD32F350xx series has a comparator, there is no one in GD32F330/F310xx;
3. GD32E230xx series adds 1K OTP area, which is not available in GD32F3x0 series;
4. GD32F350xx series has USBFS, HDMI-CEC and DAC peripheral, GD32F330/F310xx series and GD32E230xx series do not have these peripheral.

Please check for details in Table 3-1. GD32F3x0 series and gd32E230xx series resources comparison overview and Table 3-2. GD32F3x0 series and GD32E230xx series peripheral address comparison overview.

Table 3-1. GD32F3x0 series and gd32E230xx series resources comparison overview

<table>
<thead>
<tr>
<th>Peripheral</th>
<th>GD32F310xx</th>
<th>GD32F330xx</th>
<th>GD32F350xx</th>
<th>GD32E230xx</th>
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<tbody>
<tr>
<td>Core</td>
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<td>Cortex-M4</td>
<td>Cortex-M4</td>
<td>Cortex-M23</td>
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<tr>
<td>Flash</td>
<td>16K-64K</td>
<td>16K-128K</td>
<td>16K-128K</td>
<td>16K-64K</td>
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<td>RAM</td>
<td>4K-8K</td>
<td>4K-16K</td>
<td>4K-16K</td>
<td>4K-8K</td>
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<tr>
<td>Frequency</td>
<td>72MHz</td>
<td>84MHz</td>
<td>108MHz</td>
<td>72MHz</td>
</tr>
<tr>
<td>GPTM(32bit)</td>
<td>0</td>
<td>1</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>GPTM(16bit)</td>
<td>4/5</td>
<td>4/5</td>
<td>5</td>
<td>4/5</td>
</tr>
<tr>
<td>AdvTM</td>
<td>1</td>
<td>1</td>
<td>1</td>
<td>1</td>
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<td>BaseTM</td>
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<td>1</td>
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<td>U(S)ART</td>
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<td>1/2</td>
<td>1/2</td>
<td>1/2</td>
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<td>I2C</td>
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<td>1/2</td>
<td>1/2</td>
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<td>SPI</td>
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<td>1/2</td>
<td>1/2</td>
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<td>1</td>
<td>0</td>
</tr>
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<td>HDMI-CEC</td>
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<td>0</td>
<td>1</td>
<td>0</td>
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</tr>
<tr>
<td>COMP</td>
<td>0</td>
<td>0</td>
<td>2</td>
<td>1</td>
</tr>
<tr>
<td>ADC</td>
<td>1(9)/1(10)</td>
<td>1(9)/1(10)/1(16)</td>
<td>1(10)/1(16)</td>
<td>1(9)/1(10)</td>
</tr>
<tr>
<td>DAC</td>
<td>0</td>
<td>0</td>
<td>1</td>
<td>0</td>
</tr>
<tr>
<td>Operating Voltage</td>
<td>2.6-3.6V</td>
<td>2.6-3.6V</td>
<td>2.6-3.6V</td>
<td>1.8-3.6V</td>
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<td>Temperature Range</td>
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<td>-40-85°C</td>
<td>-40-85°C</td>
<td>-40-85°C</td>
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</tbody>
</table>

Note: The above "/" represents a variety of situations, which need to be distinguished according to the specific chip part number.

Table 3-2. GD32F3x0 series and GD32E230xx series peripheral address comparison
## Overview

<table>
<thead>
<tr>
<th>Peripheral</th>
<th>BUS</th>
<th>GD32F3x0</th>
<th>GD32E230xx</th>
</tr>
</thead>
<tbody>
<tr>
<td>GPIOF</td>
<td>AHB2</td>
<td>0x48001400</td>
<td>0x48001400</td>
</tr>
<tr>
<td>GPIOD</td>
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<td>GPIOC</td>
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<td>0x48000800</td>
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<td>GPIOB</td>
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<td>DBG</td>
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<td>0x40015800</td>
</tr>
<tr>
<td>TIMER16</td>
<td>APB2</td>
<td>0x40014800</td>
<td>0x40014800</td>
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<tr>
<td>TIMER15</td>
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<td>USART0</td>
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<td>0x40013800</td>
<td>0x40013800</td>
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<tr>
<td>SPI0/I2S0</td>
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<td>0x40013000</td>
<td>0x40013000</td>
</tr>
<tr>
<td>TIMER0</td>
<td></td>
<td>0x40012C00</td>
<td>0x40012C00</td>
</tr>
<tr>
<td>ADC</td>
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<td>EXTI</td>
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<td>0x40010400</td>
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<td>SYSCFG+CMP</td>
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<td>0x40010000</td>
<td>0x40010000</td>
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<tr>
<td>CTC</td>
<td>APB1</td>
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<td>CEC</td>
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<td>DAC</td>
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<td>PMU</td>
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<td>0x40007000</td>
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<td>0x40005800</td>
<td>0x40005800</td>
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<td>I2C0</td>
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<td>0x40002C00</td>
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<td>RTC</td>
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<td>TIMER13</td>
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<td>0x40002000</td>
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<td>TIMER5</td>
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<td>TIMER1</td>
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<td>SRAM</td>
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<td>0x20000000</td>
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<tr>
<td>Option Byte</td>
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<tr>
<td>Main Flash</td>
<td></td>
<td>0x08000000</td>
<td>0x08000000</td>
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<tr>
<td>System Memory</td>
<td></td>
<td>0x1FFFFFFC00</td>
<td>0x1FFFFFFC00</td>
</tr>
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</table>
## Migration from GD32E230 series to GD32F3x0 series

<table>
<thead>
<tr>
<th>OTP</th>
<th>-</th>
<th>0x1FFF7000</th>
</tr>
</thead>
</table>

**OTP** - One Time Programmable memory.
4. **Comparison of development tools**

GD32F3x0 can be developed by using Keil4 and Keil5 of MDK for arm. It is recommended to install version 4.74 or above when using Keil4; Using Keil5, it is recommended to install version 5.20 or above. You can also use IAR for ARM development. It is recommended to install IAR 6.3 or above, As shown in Table 4-1. Comparison of IDE environment between GD32F3x0 series and GD32E230xx series.

**Table 4-1. Comparison of IDE environment between GD32F3x0 series and GD32E230xx series**

<table>
<thead>
<tr>
<th>MCU series</th>
<th>GD32F3x0</th>
<th>GD32E230xx</th>
</tr>
</thead>
<tbody>
<tr>
<td>KEIL</td>
<td>Both Keil4 and Keil5 support</td>
<td>KEIL 5.25 or above</td>
</tr>
<tr>
<td>IAR</td>
<td>IAR 6.3 or above</td>
<td>IAR 8.1 or above</td>
</tr>
</tbody>
</table>

GD32F3x0 can be developed with debugging tools such as J-LINK, ULINK and GD-LINK. As shown in Table 4-2. Comparison of GD32F3x0 series and GD32E230xx series debugging tools.

**Table 4-2. Comparison of GD32F3x0 series and GD32E230xx series debugging tools**

<table>
<thead>
<tr>
<th>MCU series</th>
<th>GD32F3x0</th>
<th>GD32E230xx</th>
</tr>
</thead>
<tbody>
<tr>
<td>JLINK</td>
<td>JLINK ob, V8 and V9 all support</td>
<td>Only JLINK V9 and above</td>
</tr>
<tr>
<td>ULINK</td>
<td>support</td>
<td>support</td>
</tr>
<tr>
<td>GDLINK</td>
<td>support</td>
<td>support</td>
</tr>
</tbody>
</table>
5. **Software environment settings**

5.1. **Using Keil to develop GD32F3x0**

At present, the common MDK for arm versions on the market include Keil4 and Keil5: it is recommended to install version 4.74 or above for Keil4 and version 5.20 or above for Keil5.

5.1.1. **Add GD32F3x0 MCU device in Keil4**

1. Download GD32F3x0 series plug-ins from gd32mcu website.

   **Figure 5-1. GD32F3x0 plug-in package details**

   ![GD32F3x0 plug-in package details](image)

   2. Double click the installation file to install the plug-in to the directory of Keil4. Generally, it will be selected by default. If Keil4 and Keil5 are both installed, it needs to be selected manually.

   **Figure 5-2. Installation diagram of GD32F3x0 Series MCU plug-in package (Keil4)**

   ![Installation diagram of GD32F3x0 Series MCU plug-in package (Keil4)](image)
3. After successful installation, reopen Keil4, and the drop-down option of "Database" can appear in "Options for Target ->Device". Click to view the GD32F3x0 part number.

Figure 5-3. Successful installation of GD32F3x0 Series MCU plug-in package (Keil4)

4. For the smooth progress of subsequent debugging, it is recommended to check whether there is a download algorithm under the installation path. You can check it in the following way: open a project, select the device as GD32F3x0, and then "Options for Target -> Debug ->Settings -> Flash Download-> Add". If there is a flash download algorithm of GD32F3x0 in the drop-down option, the installation is successful.

Figure 5-4. GD32F3x0 series flash algorithm file selection diagram (Keil4)
5.1.2. Add GD32F3x0 MCU device in Keil5

1. Download GD32F3x0 series plug-ins from gd32mcu website.

**Figure 5-5. GD32F3x0 plug-in package details**

2. Extract and install it into the directory of Keil5.

**Figure 5-6. Installation diagram of GD32F3x0 Series MCU plug-in package (Keil5)**

3. After installation, reopen Keil5 project, and you can find GD32F3x0 device in "Options for Target -> Device".
4. Add the flash algorithm in "Options for Target -> Debug ->Settings ->Flash Download", and the algorithm of GD32F3x0 will appear, which indicates that the installation is successful. Debug and download is now available.

Figure 5-8. GD32F3x0 series flash algorithm file selection diagram (Keil5)

5. Open Keil5 project file in Keil4 environment

If Keil5 environment is not installed, Keil4 environment can also be used to compile Keil5 project files. The method is to modify the suffix of the project file, and change the suffix
"xxxx. uvproj" of Keil5 project file to "xxxx. uvproj", then Keil4 can be used for development.

6. Open Keil4 project file in Keil5 environment

If you use Keil5 environment to open the Keil4 project file, There will be no MCU devices found. In this case, you can directly modify the suffix of the Keil4 project file "xxxx.uvproj" to "xxxx.uvprojx", then Keil5 can be used for development.

5.2. Debugging and simulating GD32F3x0 with GD-Link

Debugging and simulating GD MCU with GD-Link, the hardware needs to be connected to the development board with GD-Link tool, and the specific configuration of the IDE is as follows.

1. Open a GD32F3x0 project and select "CMSIS-DAP Debugger" in "Options for Target -> Debug". Some customers reported that this drive option could not be found because the MDK version is too low and only Keil4 The "CMSIS-DAP Debugger" option is only supported for versions above 4.74 and Keil5.

Figure 5-9. Select the "CMSIS-DAP Debugger" option in the Debug interface (Keil4)

2. In "Options for Target > Utilities", we also have to choose "CMSIS-DAP Debugger" option.
3. In the "Options for Target > Debug ->Settings" check SWJ and Port select SW. "0xXBAXXXXX" will appear in the idcode in the right box, indicates that the target MCU device is successfully connected.

4. Add the flash algorithm of GD32F3x0 in "Options for Target -> Debug ->Settings -> Flash Download".
5. Click the shortcut in the red box in **Figure 5-13. Schematic diagram of GD-Link simulation (Keil4)** to start debugging, and you can use GD-Link for simulation.

5.3. **Debugging and simulating GD32F3x0 with J-Link**

Debugging and simulating GD MCU with J-Link, The hardware needs to be connected to the
Development board with J-Link tool, and the specific configuration of the IDE is as follows:

1. Open a GD32F3x0 project file and select "J-LINK/J-Trace Cortex" in "Options for Target -> Debug".

Figure 5-14. Select the "J-LINK/J-Trace Cortex" option in the Debug interface (Keil4)

2. In "Options for Target > Utilities", we also have to choose "J-LINK/J-Trace Cortex" option.

Figure 5-15. Select the "J-LINK/J-Trace Cortex" option in the Utilities interface (Keil4)

3. In the "Options for Target > Debug ->Settings" Port select SW. "0xXBAXXXXX" will appear in the idcode in the right box, indicates that the target MCU device is successfully connected.

Figure 5-16. J-Link tool successfully connected to the target MCU(Keil4)

4. Add the flash algorithm of GD32F3x0 in "Options for Target -> Debug ->Settings -> Flash Download".
5. Click the shortcut in the red box in Figure 5-18. Schematic diagram of J-Link simulation(Keil4) to start debugging, and you can use J-Link for simulation.

5.4. Using IAR to develop GD32F3x0

There are many versions of IAR, and the compatibility between versions is not good. If you use it for the first time, it is recommended to install versions above 7.3. After installing IAR, add the device of GD according to this document for debugging.
5.4.1 Add gd32F3x0 MCU device in IAR

1. Download GD32F3x0 series plug-ins: IAR_GD32F3x0_ADDON_2.0.0.exe.
2. Run IAR_GD32F3x0_ADDON_2.0.0.exe, click start to start installing the plug-in.

Figure 5-19. Installation diagram of GD32F3x0 Series MCU plug-in package (IAR)

3. After the installation is successful, click Finish to end the plug-in installation.

Figure 5-20. Successful installation of GD32F3x0 Series MCU plug-in package (IAR)

5.4.2 Debugging GD32F3x0 in IAR

In the previous section, we have added the plug-in of GD32F3x0 series. In this section, we will introduce how to use it.

1. There are two ways to use IAR to compile GD MCU. One is to use the existing project for modification, and the other is to re-establish the project. Here, we will not introduced how to establish the project. The project establishment of GD is consistent with that of other
Figure 5-21. Select the GD device in the IAR "Options" interface

2. IAR after version 6.1 does not need to add CMSIS files (core_cm3.c and core_cm3.h), but you need to check use CMSIS in "General Options->Library Configuration". If the software code uses printf function, you also need to modify the "Library" to "FULL".
3. The Link file of the chip will be selected by default according to the device when establishing the project, but you should still have the habit of checking before compiling. Check whether the ICF file is configured and correct.

4. Configure the "Debugger->Setup" option. The newly created project is simulator option by default. If debugging is required, you need to choose according to the actual situation: use GD-Link to select CMSIS DAP (poor compatibility, not recommended under IAR) or J-Link to select J-Link/J-Trace.
5. Configure the "Debugger->Download" option. The new project may not be configured with the download option. If we need to debug the code, we must check the "User flash loader" option and ensure that the "board file" is accurate, otherwise the program cannot be downloaded to the chip normally.

Figure 5-25. Configure flash loader in IAR "Options" interface
6. **Steps of GD32E23x firmware library adapting to GD32F3x0 Series MCU**

This chapter will use GD32E23x_Firmware_Library_V1.1.1 take the project in the template as an example to introduce how to adapt GD32F3x0 series MCU.

1. Open Keil project.

   **Figure 6-1. Open GD32E23x Keil project**

2. After opening the project, "Options for Target -> Device", select GD32F3x0 MCU part number.

   **Figure 6-2. Select GD32F3x0 device in GD32E23x project**

3. Add the flash algorithm of GD32F3x0 in "Options for Target -> Debug ->Settings -> Flash Download".
4. Copy Cortex M4 kernel files to:

\texttt{x:\ GD32E23x\_Firmware\Library\V1.1.1\Firmware\CMSIS.}

Figure 6-4. Add Cortex M4 kernel files to GD32E23x firmware library

5. Modify the contents of the "gd32e23x.h" in GD32E23x firmware library.

Figure 6-5. Modify the contents of "gd32e23x.h"

<table>
<thead>
<tr>
<th>Table 6-1. Modify the contents of &quot;gd32e23x.h&quot;</th>
</tr>
</thead>
<tbody>
<tr>
<td>After modification</td>
</tr>
<tr>
<td>#include &quot;core_cm4.h&quot;</td>
</tr>
<tr>
<td>#define __CM4_REV 0x0001</td>
</tr>
</tbody>
</table>
Migration from GD32E230 series to GD32F3x0 series

6. GD32E230xx does not support interrupt grouping, so there is no "void nvic_priority_group_set (uint32_t nvic_prigroup)" function in the firmware library. We need to add corresponding content in the firmware library.

Table 6-2. Modify the contents of "gd32e23x_misc.h"

<table>
<thead>
<tr>
<th>Priority Group Preemption Priority and Subpriority</th>
</tr>
</thead>
<tbody>
<tr>
<td>NVIC_PRIGROUP_PRE0_SUB4</td>
</tr>
<tr>
<td>NVIC_PRIGROUP_PRE1_SUB3</td>
</tr>
<tr>
<td>NVIC_PRIGROUP_PRE2_SUB2</td>
</tr>
<tr>
<td>NVIC_PRIGROUP_PRE3_SUB1</td>
</tr>
<tr>
<td>NVIC_PRIGROUP_PRE4_SUB0</td>
</tr>
</tbody>
</table>

/* set the priority group */
void nvic_priority_group_set(uint32_t nvic_prigroup);

Table 6-3. Modify the contents of "gd32e23x_misc.c"

void nvic_priority_group_set(uint32_t nvic_prigroup)
{
    /* set the priority group value */
    SCB->AIRCR = NVIC_AIRCR_VECTKEY_MASK | nvic_prigroup;
}

7. GD32E230xx only supports level 4 priority, not sub priority. GD32F3x0 supports both priority and sub priority. The corresponding contents need to be modified in the firmware library.

Table 6-4. Modify the contents of "gd32e23x_misc.h"

/*/ enable NVIC request */
void nvic_irq_enable(uint8_t nvic_irq, uint8_t nvic_irq_pre_priority, uint8_t nvic_irq_sub_priority);

Table 6-5. Modify the contents of "gd32e23x_misc.c"

void nvic_irq_enable(uint8_t nvic_irq, uint8_t nvic_irq_pre_priority, uint8_t nvic_irq_sub_priority)
{
    uint32_t temp_priority = 0x00U, temp_pre = 0x00U, temp_sub = 0x00U;
    /* use the priority group value to get the temp_pre and the temp_sub */
    switch ((SCB->AIRCR) & (uint32_t)0x700U) {
        case NVIC_PRIGROUP_PRE0_SUB4:

Migration from GD32E230 series to GD32F3x0 series

```
    temp_pre = 0U;
    temp_sub = 0x4U;
    break;
    case NVIC_PRIGROUP_PRE1_SUB3:
        temp_pre = 1U;
        temp_sub = 0x3U;
        break;
    case NVIC_PRIGROUP_PRE2_SUB2:
        temp_pre = 2U;
        temp_sub = 0x2U;
        break;
    case NVIC_PRIGROUP_PRE3_SUB1:
        temp_pre = 3U;
        temp_sub = 0x1U;
        break;
    case NVIC_PRIGROUP_PRE4_SUB0:
        temp_pre = 4U;
        temp_sub = 0x0U;
        break;
    default:
        nvic_priority_group_set(NVIC_PRIGROUP_PRE2_SUB2);
        temp_pre = 2U;
        temp_sub = 0x2U;
        break;
    }
    /* get the temp_priority to fill the NVIC->IP register */
    temp_priority = (uint32_t)nvic_irq_pre_priority << (0x4U - temp_pre);
    temp_priority |= nvic_irq_sub_priority &(0x0FU >> (0x4U - temp_sub));
    temp_priority = temp_priority << 0x04U;
    NVIC->IP[nvic_irq] = (uint8_t)temp_priority;
    NVIC->ISER[nvic_irq >> 0x05U] = (uint32_t)(0x01U << (nvic_irq & (uint8_t)0x1FU));
```

8. The flash of GD32F3x0 is zero waiting. GD32E230xx series needs to configure the waiting cycle, so the function of waiting cycle can be removed.

Table 6-6. Remove the function of waiting period in GD32E23x project

```
FMC_WS = (FMC_WS & (~FMC_WS_WSCNT)) | WS_WSCNT_2;
```

9. The flash of GD32E230xx supports 32-bit and 64-bit programming, and the flash of GD32F3x0 supports 32-bit word and half word programming. If 64-bit programming is used in the application code, it needs to be modified to 32-bit word or half word programming, and half word programming needs to be added to the GD32E230xx firmware library.
Table 6-7. Add half word programming to "gd32e23x_fmc.h" of GD32E23x project

/* FMC program a half word at the corresponding address */
fmc_state_enum fmc_halfword_program(uint32_t address, uint16_t data);

Table 6-8. Add half word programming to "gd32e23x_fmc.c" of GD32E23x project

fmc_state_enum fmc_halfword_program(uint32_t address, uint16_t data)
{
    fmc_state_enum fmc_state = fmc_ready_wait(FMC_TIMEOUT_COUNT);
    
    if(FMC_READY == fmc_state){
        /* set the PG bit to start program */
        FMC_CTL |= FMC_CTL_PG;
        REG16(address) = data;
        /* wait for the FMC ready */
        fmc_state = fmc_ready_wait(FMC_TIMEOUT_COUNT);
        /* reset the PG bit */
        FMC_CTL &= ~FMC_CTL_PG;
    }
    /* return the FMC state */
    return fmc_state;
}

10. If TIMER5 is used in the project, because GD32F3x0 remove this TIMER5(Except GD32F350xx), the code of TIMER5 needs to be changed to other timer.
11. Compile GD32E23x project, so far, you can use the modified GD32E23x firmware library for software development in GD32F3x0 series MCU.
7. Steps to replace GD32E23x project library with GD32F3x0 Library

This chapter will use the projects in "GD32E23x_Firmware_Library_V1.1.1\Template" and "GD32F3x0_Firmware_Library_V2.2.0\Template" as examples.

1. Copy the files in "GD32F3x0_Firmware_Library_V2.2.0\Firmware\CMSIS" to the "GD32E23x_Firmware_Library_V1.1.1\Firmware\CMSIS" folder.

   Figure 7-1. Copy h file in CMSIS of GD32F3x0 firmware library to GD32E23x

2. Copy the Include and Source folders in "GD32F3x0_Firmware_Library_V2.2.0\Firmware\CMSIS\GD\GD32F3x0" and replace them to the "GD32E23x_Firmware_Library_V1.1.1\Firmware\CMSIS\GD\GD32E23x" folder.

   Figure 7-2. Copy and replace the Include and Source files in CMSIS under GD32F3x0 firmware library into GD32E23x firmware library

3. Copy the Include and Source folders in "GD32F3x0_Firmware_Library_V2.2.0\Firmware\GD32F3x0_standard_peripheral" and replace them to the "GD32E23x_Firmware_Library_V1.1.1\Firmware\GD32E23x_standard_peripheral" folder.

   Figure 7-3. Copy and replace the Include and Source files in standard_peripheral under GD32F3x0 firmware library into GD32E23x firmware library

4. Copy the "gd32f3x0_libopt.h" file in "GD32F3x0_Firmware_Library_V2.2.0\Template" into "GD32E23x_Firmware_Library_V1.1.1\Template".

   Figure 7-4. Copy the "gd32f3x0_libopt.h" file in GD32F3x0 firmware library into
5. Open the Keil project under the template file in the GD32E23x firmware library.

Figure 7-5. Open the Keil project under the template file in the GD32E23x firmware library

6. A yellow triangle mark on the left side of the engineering interface indicates that the original file no longer exists because the old file has been replaced in the previous file replacement steps. At this time, you only need to remove all the files marked in yellow. Among them, "gd32e230c_eval.c" is the supporting configuration of the development board. If it is not used in the actual project, it can be transplanted, and then add the corresponding GD32F3x0 files.
7. Modify the "#include "gd32e23x.h" "statement contained in the" main. c" and "systick. c" files in the project to "#include "gd32f3x0.h"" statement, and delete the "#include"gd32e230c_eval. h"" statement. Then reselect the MCU device and flash algorithm.

Figure 7-7. Modify the contents of "main.c", "systick.c" files
8. Since GD32E230xx does not support the bit length of the configuration priority group, after transplanting the GD32F3x0 library, when there is a configuration of using interrupt in the application code, the application code needs to add the "void nvic_priority_group_set(uint32_t nvic_prigroup)" function.

**Table 7-1. nvic_priority_group_set function**

```c
/* set the priority group */
void nvic_priority_group_set(uint32_t nvic_prigroup);```

Moreover, GD32E230xx only supports level 4 preemption priority and does not support sub priority. Therefore, after transplantation, the interrupt enabling function needs to be changed to the function shown in **Table 7-2. nvic_irq_enable function**.
Table 7-2. nvic_irq_enable function

/* set the priority group */
void nvic_irq_enable(uint8_t nvic_irq, uint8_t nvic_irq_pre_priority, uint8_t nvic_irq_sub_priority);

9. If TIMER5 is used in the project, because GD32F3x0 remove this TIMER5 (Except GD32F350xx), the code of TIMER5 needs to be changed to other timer.

10. Compile the project. If there is an error, modify it according to the prompt. Usually, the prompt is that "#include "gd32e23x.h"" in the code is not modified to "#include "gd32f3x0.h"", and modify it according to the prompt. So far, the project has been transplanted successfully, and the development of GD32F3x0 Series MCU can be carried out.
8. Revision history

Table 8-1. Revision history

<table>
<thead>
<tr>
<th>Revision No.</th>
<th>Description</th>
<th>Date</th>
</tr>
</thead>
<tbody>
<tr>
<td>1.0</td>
<td>Initial Release</td>
<td>Mar.15 2022</td>
</tr>
</tbody>
</table>
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